### Map Technology for Evidence-Based Trails

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#### 500 ft

#### 100 m



#### Sustainable



#### Built to conventional standards

## Ad hoc trail design

#### Unsustainable

#### Sustainable



#### Built to conventional standards

Ad hoc trail design

#### Unsustainable

- Decrease cost and increase quality of trails
- Share methods with the broader community
- Develop approaches that are specific to a particular locality
- Have a bit of geeky fun

## OUT GOALS R



#### **Collect** data

- **Develop metrics**
- **Controlled design process**
- Systematically compare options

#### What might it mean to make "Evidencebased trails"



#### Data sources

- Lidar
- Photogrammetry
- Multispectral imagery
- Tracklines
- User surveys
- Computer model outputs





## What metrics might we want?

- Environmental / aesthetic impact
- Build effort / cost
- Maintenance effort / cost
- Probability of catastrophic failure
- Risk to hikers
- Usability / user experience



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## Approaches for some future talk

- Predictors of shortcutting
- Synthesized user track lines to detect problem sites. Maybe get data by sponsoring a trail race?
- Numerical models to develop trail alignment proposals
- Cost models for building and maintaining trails
- Monitoring mm-scale topographic change









![](_page_11_Picture_0.jpeg)

![](_page_12_Picture_0.jpeg)

#### 100 m

![](_page_12_Picture_3.jpeg)

![](_page_13_Picture_0.jpeg)

![](_page_14_Picture_0.jpeg)

#### 100 m

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![](_page_14_Picture_3.jpeg)

#### Lidar (DGGS)

![](_page_15_Figure_1.jpeg)

![](_page_15_Picture_2.jpeg)

![](_page_16_Picture_0.jpeg)

![](_page_16_Figure_2.jpeg)

![](_page_16_Picture_4.jpeg)

![](_page_17_Picture_0.jpeg)

#### 100 m

![](_page_17_Picture_3.jpeg)

![](_page_18_Picture_0.jpeg)

#### 100 m

![](_page_18_Picture_3.jpeg)

![](_page_19_Picture_0.jpeg)

![](_page_20_Picture_0.jpeg)

![](_page_21_Picture_0.jpeg)

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![](_page_25_Picture_0.jpeg)

![](_page_26_Picture_0.jpeg)

![](_page_27_Picture_0.jpeg)

#### **Trail Profiles**

![](_page_28_Figure_1.jpeg)

Distance (meters)

![](_page_29_Picture_0.jpeg)

#### 100 m

![](_page_29_Picture_3.jpeg)

![](_page_30_Picture_0.jpeg)

![](_page_31_Picture_0.jpeg)

![](_page_32_Picture_0.jpeg)

# 500 ft 100 m

![](_page_32_Picture_2.jpeg)

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![](_page_33_Picture_2.jpeg)

![](_page_34_Figure_0.jpeg)

#### What is Lidar? **3D Laser Scanning**

![](_page_34_Figure_2.jpeg)

![](_page_35_Picture_0.jpeg)


Point Cloud: Vertical Plan View



#### Derived from Lidar: Contours and Relief Shading

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Horizontal Distance (meters)











Tread Width 18"-36" Shoulder Clearance 12"-18









#### Vegetation Density: Fraction of Lidar pulses that are blocked within two meters of the ground











## 500 ft

#### 100 m

Lidar (DGGS)



# 500 ft

#### Photogrammetry 100 m (Mark Laker, USFWS)



### 500 ft

Photogrammetry 100 m (Mark Laker, USFWS)



home services about ORX

clean granite has been attracting rock climbers for over 30 years.

We were interested in exploring how computerized 3D modeling can aid in visualizing complex or difficult terrrain. In this case, we wanted to see how a 3D model of a popular rock climbing destination can make terrain data uniquely accessible.



Click & drag to zoom and rotate the model













# Snow Imagery: June 13th





# July 16th

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### **Glen** Alps

Flattop

**Canyon Rd Trailhead** 

223

# **Little Omalley** 55050



Non.




















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